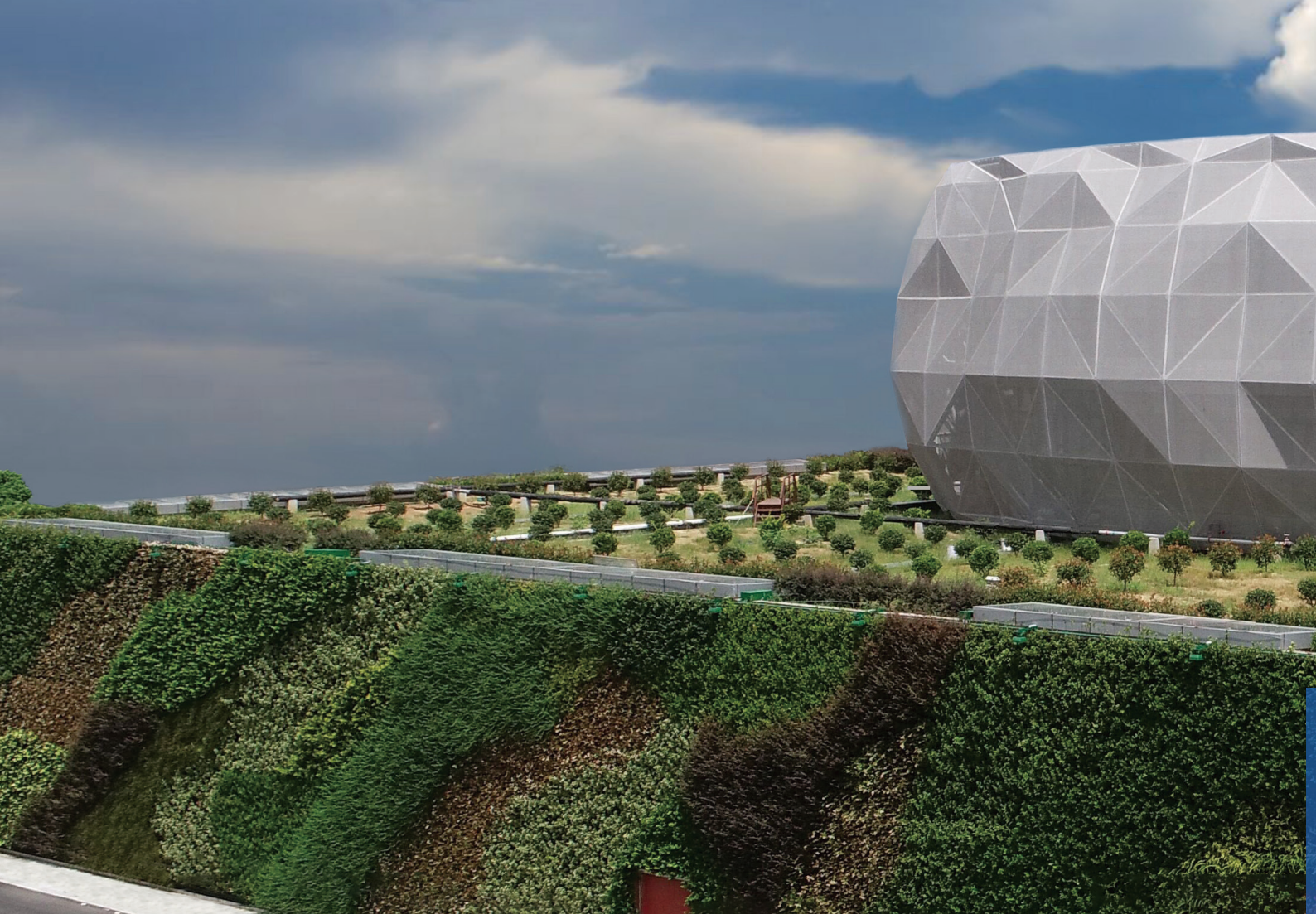


# AxN Series Servo Drive

AxN系列伺服驱动器





## Company Profile 企业简介

宁波菲仕技术股份有限公司（简称：菲仕技术）成立于2001年，由民营控股、先进制造产业投资基金和宁波通商集团等战略投资人参股，公司致力于以“高效节能、精准控制”电驱动技术为核心的创新及产业化，为运动控制和能量转换领域提供系统产品和综合解决方案，经过多年品牌沉淀，菲仕已成为一家集研发、生产、销售为一体，拥有国内外多家控股子公司的集团化创新型高科技企业。

Ningbo Physis Technology Co., Ltd. (hereinafter referred to as Physis) was founded in 2001. Physis always devotes to innovation and industrialization of electrical drive technology, provides servo products and solutions for the field of motion control & energy conversion. After years of brand development and accumulation, Physis becomes a collectivized & innovative high-tech enterprise, which collects together R&D, manufacturing and sales, and has a numbers of domestic and overseas subsidiaries.



6 大生产基地  
Manufacturing bases



2 大研发中心  
R&D center



17 个海内外分支机构  
Subsidiaries



40+ 远销国家和地区  
Sold in countries and regions

## Global presence 全球布局

### 立足全国 放眼全球

总部“永动谷”落户中国宁波北仑，在国内产业链完善的宁波、株洲、天津、赣州建立大型生产基地。建立国内外分子公司 17 家，合作伙伴百余家，形成覆盖全国、面向全球市场的营销服务网络，逐步落地国际化战略。

Physis has established large-scale production bases in Ningbo, Zhuzhou, Tianjin, and Guangzhou, which have a complete domestic industrial chain.

It has established 17 domestic and foreign subsidiaries and more than 100 partners, formed a marketing service network covering the whole country and facing the global market, and gradually implemented the internationalization strategy.

菲仕研发的新一代高性能伺服驱动器，其额定电流输出能力覆盖 9A ~ 200A，支持 EtherCAT、CANOpen 和 Modbus 等多种现场总线，支持多种主流编码器，非常适合搭建高性能伺服系统的应用场合。搭配菲仕永磁同步伺服电机，为纺织机械、印刷机械、包装机械、塑料机械、机器人、医疗生产设备、风力发电、光伏等伺服应用市场提供个性化高性能伺服解决方案。

AxN series servo drive is the new generation of high performance servo drive with rated current output capacity of 9A~200A, supports EtherCAT, CANOpen and Modbus , supports a variety of mainstream encoders, and are suitable for applications that need high performance servo systems. Physis can provide personalized high performance servo solutions for textile machinery, printing machinery, packaging machinery, rubber plastic machinery, medical production equipment, wind power, photovoltaic and other industries.

#### 紧凑的外形尺寸

对比上一代产品，体积缩小 16% ~ 20%，重量减轻 25% ~ 35%

#### Compact Size

16% ~ 20% size reduction, 25% ~ 35% weight reduction, compare to predecessor

#### 内置可编程 PLC

更智能，方便脱离上位机运行

#### Built in Programmable PLC

Intelligent, can run independently without controller

#### 可编程显示模块

抛弃传统数码管显示局限，自由定制显示内容

#### Programmable Display Module

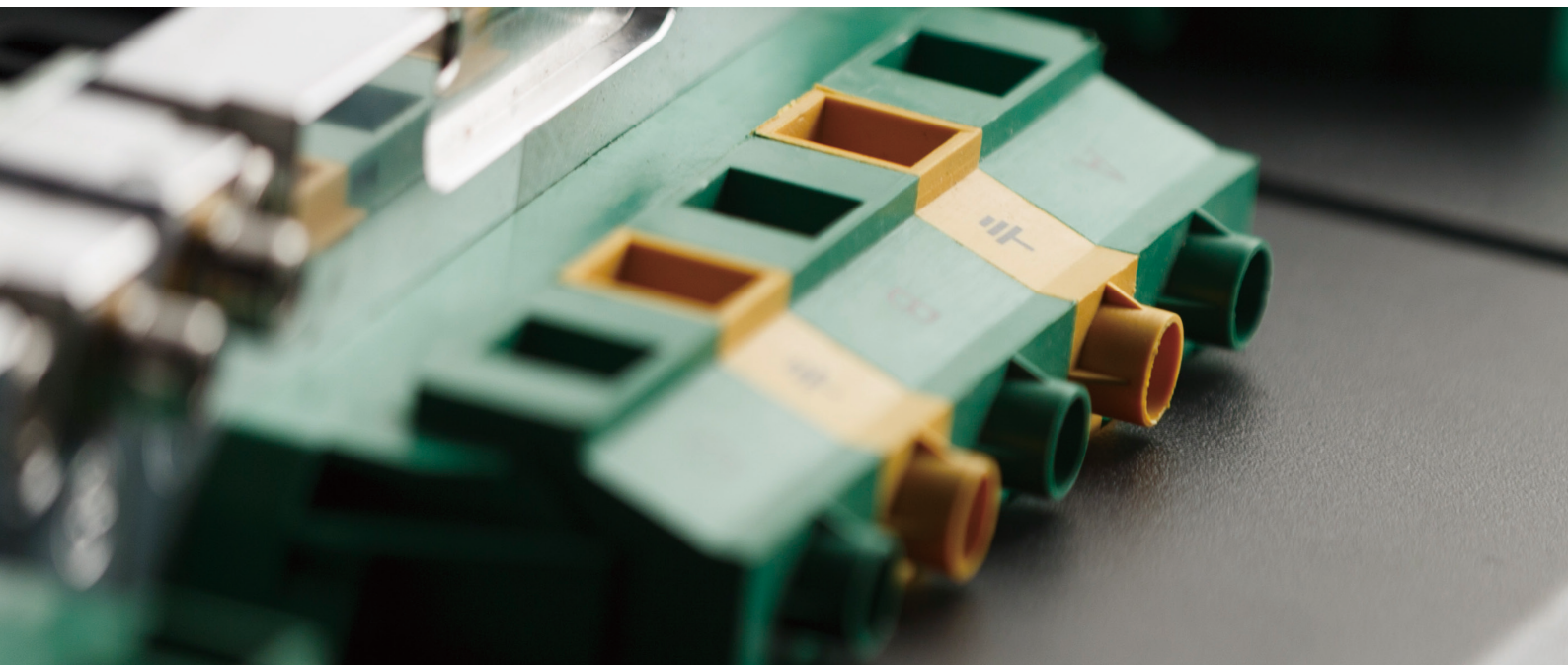
Customize display contents, abandon the limitation of traditional digital display

#### 主流高速现场总线支持

EtherCAT、CANOpen、Modbus

#### Main Stream High Speed Fieldbus

EtherCAT、CANOpen、Modbus



## 高速 I/O 端口    隔离 I/O 端口 ( 选配 )

|         |         |
|---------|---------|
| 4 路模拟输入 | 3 路模拟输入 |
| 2 路模拟输出 | 2 路模拟输出 |
| 8 路数字输入 | 8 路数字输入 |
| 4 路数字输出 | 2 路数字输出 |

## 丰富的位置传感器支持

正余弦编码器  
Endat 编码器  
增量编码器  
旋转变压器  
Hiperface 编码器  
Nikon 编码器  
Tamagawa 编码器

## 齐全的 PC 软件

在线配置软件: Cockpit 3  
集成开发环境: LogicLab  
软件示波器: Softscope  
支持中英意三国语言

## 灵活安装

支持柜内安装、穿墙安装和冷却板安装, 可使用内置风冷和外置水冷

## High Speed I/O    Insulated I/O (Optional)

|                   |                   |
|-------------------|-------------------|
| 4 Analog Inputs   | 3 Analog Inputs   |
| 2 Analog Outputs  | 2 Analog Outputs  |
| 8 Digital Inputs  | 8 Digital Inputs  |
| 4 Digital Outputs | 2 Digital Outputs |

## Various Position Sensor Support

Sincos Encoder  
Endat Encoder  
Incremental Encoder with Hall  
Resolver  
Hiperface Encoder  
Nikon Encoder  
Tamagawa Encoder

## Complete PC Software

Online configure and debug software: Cockpit 3  
Integrated development environment: LogicLab  
Software oscilloscope: Softscope  
Multi-language support: English, Chinese and Italian

## Flexible Installation

Support wall mounting, feed-through mounting and cold plate mounting, can use internal air cooling and external water cooling



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# Order Code 订货代码

AxN                      110.250    .4                      C0    0    0                      F                      00    00

输出电流：  
09.30, 16.30, 15.30, 22.44, 35.70,  
50.100, 70.140, 90.150, 110.200,  
110.250, 150.300, 200.400  
例：  
110.250  额定 110A / 峰值 250A

Output Current：  
09.30, 16.30, 15.30, 22.44, 35.70,  
50.100, 70.140, 90.150 110.200,  
110.250, 150.300, 200.400  
Example：  
110.250  Rated 110A / Peak 250A

主电源电压类型：  
150~380Vac  三相

Main Supply Voltage Type：  
150~380Vac  Three-Phase

处理器和通讯端口：  
F0: 120MIPS μC + EtherCAT 通讯端口  
C0: 80MIPS μC + 无 EtherCAT 通讯端口

Processor and Communication Port：  
F0: 120MIPS μC + EtherCAT Communication Port  
C0: 80MIPS μC + No EtherCAT Communication Port

制动单元：  
0: 内置

Brake Module：  
0: Built-in

客户自定义：  
00: 客户自定义要求预留  
  
Customer Defined：  
00: Customer Defined  
Requirement  
Reservation

应用：  
00: 标准应用程序

Application：  
00: Standard Applications

散热：  
F: 风扇散热  
W: 水冷  
H: 油冷

Dissipate Heat：  
F: Fan Cooling  
W: Water Cooling  
H: Oil Cooling

I/O 端口：  
0: 标准 I/O 端口  
1: 标准 I/O 端口 + 扩展的隔离 I/O 端口

I / O port：  
0: Standard I / O ports  
1: Standard I / O Ports + Expansion Isolated I / O Ports

## 代码示例：

AxN 110.250.4C000F0000

额定输出电流 110A, 峰值输出电流 250A, 三相 400V 交流供电, 80MIPS μC 处理器, 去除 EtherCAT 端口, 完整制动单元以及标准 I/O 端口, 风扇冷却, 搭载标准应用程序, 无客户自定义要求。

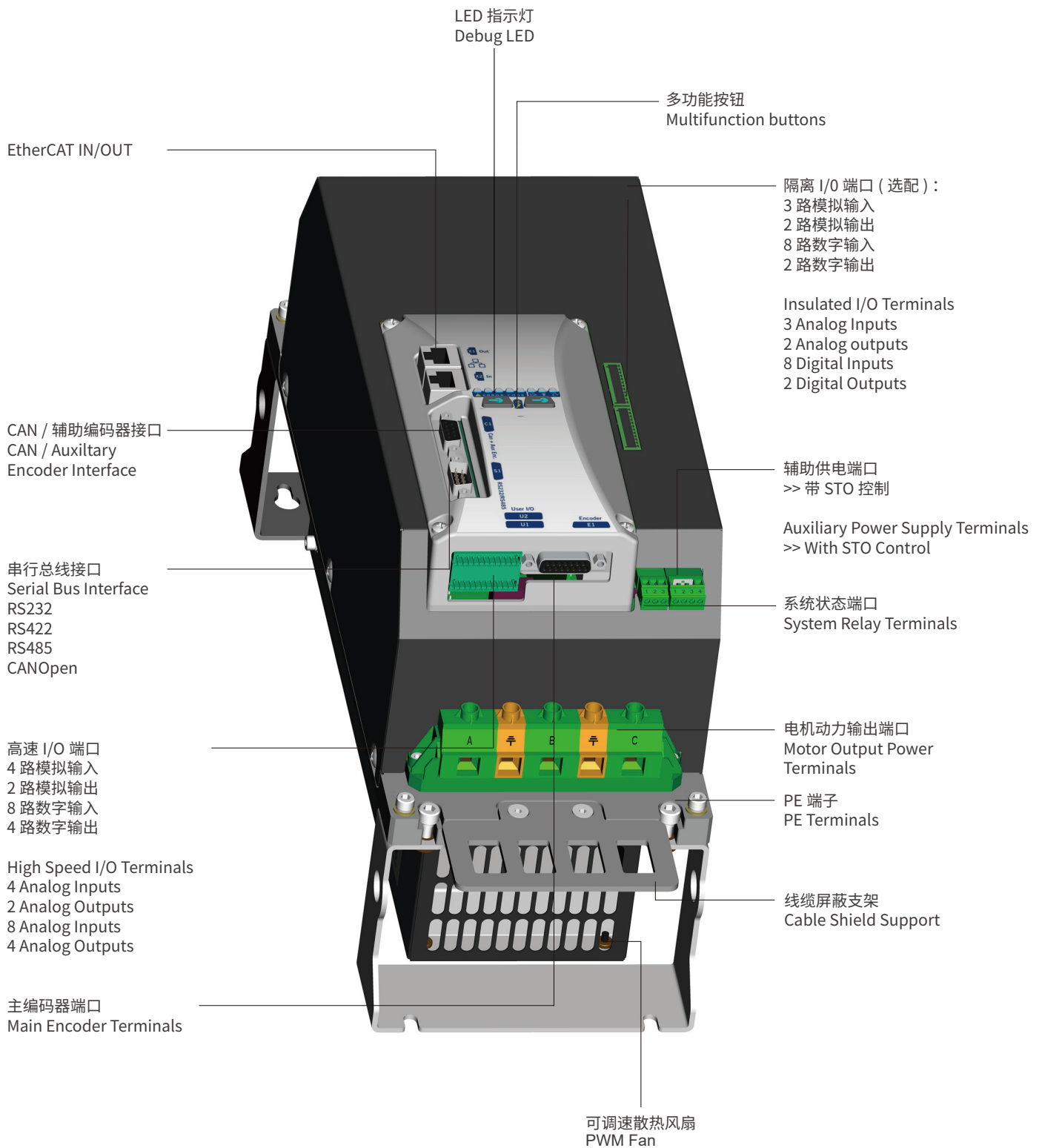
## Example Code:

AxN 110.250.4C000F0000

Rated output current 110A, peak current 250A, input voltage 400Vac, CPU 80MIPS μC, remove EtherCAT port, complete brake unit and standard I/O ports, fan cooled, standard application program, no customized requirements.

# Hardware Connections

## 硬件接口展示



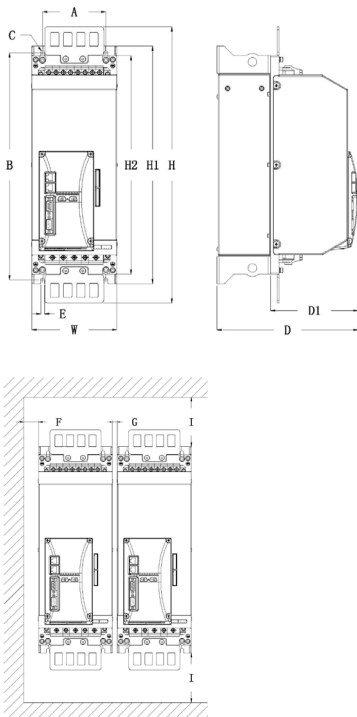
# AxN Technical Data

## AxN 系列参数

|   |  | Size1  |         | Size2   | Size3   |         |          | Size4    | Size5     |           |           |           | Size6     |
|---|--|--|---------|---------|---------|---------|----------|----------|-----------|-----------|-----------|-----------|-----------|
|   |  | 09.20.4  | 16.30.4 | 15.30.4 | 22.44.4 | 35.70.4 | 50.100.4 | 70.140.4 | 90.150.4  | 110.200.4 | 110.250.4 | 150.300.4 | 200.400.4 |
| 额定输出电流<br>Rated Current Output              |  | 09A  | 16A     | 15A     | 22A     | 35A     | 50A      | 70A      | 90A       | 110A      | 110A      | 150A      | 200A      |
| 峰值输出电流<br>Peak Current Output               |  | 20A  | 30A     | 30A     | 44A     | 70A     | 100A     | 140A     | 150A      | 200A      | 250A      | 300A      | 400A      |
| 主电源<br>Main Power Supply                    |  | 交流<br>三相 150 ~ 500Vac, 50/60Hz<br>150 ~ 500 Vac Three Phase  |         |         |         |         |          |          |           |           |           |           |           |
|   |  | 直流<br>0 ~ 800 Vdc  |         |         |         |         |          |          |           |           |           |           |           |
| 辅助电源<br>Auxiliary Power Supply              |  | 电压<br>24V ± 15%  |         |         |         |         |          |          |           |           |           |           |           |
|   |  | 2A   |         | 2A      |         | 3A      |          |          | 6A        |           | 8A        |           |           |
| 制动单元<br>Brake Module                        |  | 内置<br>Built-in   |         |         |         |         |          |          |           |           |           |           |           |
| 内部制动电阻 (阻值 / 功率)<br>Internal Brake Resistor |  | 25Ω/30W  | 18Ω/30W | 18Ω/30W | 12Ω/60W | 7Ω/60W  | 5Ω/60W   | 3.5Ω/60W | 3.5Ω/150W | 3Ω/150W   | 3Ω/150W   | 3Ω/150W   | -         |
| 外部制动电阻<br>External Brake Resistor           |  | 25Ω  | 18Ω     | 18Ω     | 12Ω     | 7Ω      | 5Ω       | 3.5Ω     | 3.5Ω      | 3Ω        | 3Ω        | 3Ω        | 3Ω        |
| 通讯总线支持<br>Fieldbus Support                  |  | CANOpen、EtherCAT、Modbus  |         |         |         |         |          |          |           |           |           |           |           |
| 位置传感器支持<br>Position Sensor Support          |  | 正弦余弦编码器 (SinCos)、Endat 编码器、增量编码器 (Incremental)、旋转变压器和 Hiperface 编码器<br>SinCos Encoder、EnDat Encoder、Digital Incremental with Hall、Resolver and Hiperface Encoder |         |         |         |         |          |          |           |           |           |           |           |
| 功能安全<br>Functional safety                   |  | STO: 安全转矩关断 符合 SIL3 IEC EN 61800-5-2:2016<br>STO: Safe Torque Off Complies with SILL3 IEC EN 61800-5-2:2016  |         |         |         |         |          |          |           |           |           |           |           |
| 配置软件<br>Management Software                 |  | Physis Tools Suite   |         |         |         |         |          |          |           |           |           |           |           |

# Dimensions

## 外形尺寸



|              |  | Size1   |         | Size2   | Size3   |         |          | Size4    | Size5    |           |           |           | Size6     |
|--------------|--|---------|---------|---------|---------|---------|----------|----------|----------|-----------|-----------|-----------|-----------|
|              |  | 09.20.4 | 16.30.4 | 15.30.4 | 22.44.4 | 35.70.4 | 50.100.4 | 70.140.4 | 90.150.4 | 110.200.4 | 110.250.4 | 150.300.4 | 200.400.4 |
| 重量<br>Weight |  | 2.5kg   |         | 6.9kg   |         | 8.8kg   |          | 13.1kg   |          | 26.8kg    |           |           | 30kg      |
| H            |  | 201.8   |         | 488     |         |         |          | 725      |          |           |           | 612       |           |
| W            |  | 96      |         | 96      |         | 150     |          | 200      |          | 286       |           |           | 350       |
| D            |  | 164.8   |         | 249     |         |         |          |          |          | 242.2     |           |           |           |
| H1           |  | -       |         | 420     |         |         |          | 652      |          |           |           | 590       |           |
| H2           |  | -       |         | 386     |         |         |          | 612      |          |           |           | 550       |           |
| D1           |  | -       |         | 155     |         |         |          |          |          | 145       |           |           |           |
| A            |  | 66      |         | 60      |         | 111.6   |          | 158.6    |          | 210       |           |           | 310       |
| B            |  | 191     |         | 401     |         |         |          | 628      |          |           |           | 566       |           |
| C            |  | 5.5     |         | 5.5     |         | 6.5     |          | 8.5      |          |           |           | 8.5       |           |
| E            |  | 5.5     |         | 5.5     |         | 6.5     |          | 8.5      |          |           |           | 8.5       |           |
| F            |  | ≥ 30    |         |         |         |         |          |          |          |           |           |           |           |
| G            |  | ≥ 10    |         |         |         |         |          |          |          |           |           |           |           |
| I            |  | ≥ 100   |         |         |         |         |          |          |          |           |           |           |           |

备注: 所有尺寸的单位均为毫米 (mm)  
Note: All dimensions are in millimeters (mm)

# AxN Size 1

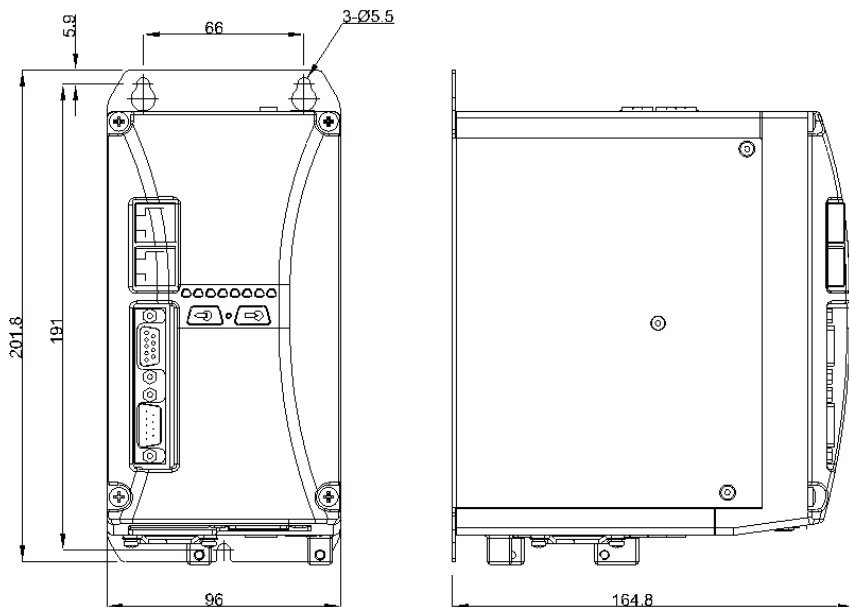
| 技术参数<br>Technical Specifications  | 符号 Symbol | AxN 09.20.4   | AxN 16.30.4    | 单位<br>Units           |
|---|-----------|---|----------------|-----------------------|
| 主电源供电电压<br>Power Supply Voltage   | $V_{in}$  | 150 ~ 500   |                | Vac                   |
|   |           | 0 ~ 800   |                | Vdc                   |
| 辅助电源供电电压<br>Auxiliary Supply Voltage                                    | $V_{aux}$ | 24V ± 15% / 2A                                      | 24V ± 15% / 3A | Vdc                   |
| 输出频率<br>Output Frequency  | f         | 0 ~ 1200  |                | Hz                    |
| 额定输出电流, $S1^{(1)}$<br>Current Output, $S1^{(1)}$                        | $I_n$     | 9   | 16             | Arms                  |
| 峰值输出电流 <sup>(1)</sup><br>Peak Current <sup>(1)</sup>                    | $I_p$     | 20  | 30             | Arms                  |
| 总功率损耗 <sup>(2)</sup><br>Power Losses Total <sup>(2)</sup>               | $P_l$     | 200   | 200            | W                     |
| 最大输出电压<br>Maximum Output Voltage  | $V_{out}$ | $V_{in} \times 0.95$                                |                | Vac                   |
| PWM 频率 <sup>(3)</sup><br>PWM Frequency <sup>(3)</sup>                   | $f_{PWM}$ | 4 / 8 / 16  |                | kHz                   |
| 额定输出功率时的效率 <sup>(1)</sup><br>Efficiency at Nominal Power <sup>(1)</sup> | ---       | 97.9  | 97.9           | %                     |
| 输入波形因数 (满负载)<br>Input form Factor(Full Load)                            | ---       | 0.9   |                | Vac                   |
| 最大制动电流<br>Maximum Braking Current                                       | ---       | 100% 峰值电流 ( $I_p$ )<br>100% of $I_p$ (Peak Current) |                | ---                   |
| 散热<br>Cooling   | ---       | 40 x 40 x 20 风扇 x1<br>1 fan 40 x 40 x 20            |                | ---                   |
| 风扇流量<br>Flow Rate   | ---       | 25.2  |                | m <sup>3</sup> / hour |
| 尺寸 (HxDxW)<br>Dimensions (HxDxW)  | ---       | 201.8 x 164.8 x 96                                  |                | mm                    |

<sup>(1)</sup> $V_{in}=380Vac$ ,  $V_{out}=V_{in} \times 0.95$ , 环境温度为 40°C, PWM 控制频率为 8kHz; /  $V_{in}=380Vac$ ,  $V_{out}=V_{in} \times 0.95$ ,  $T_{amb}=40^{\circ}C$ , Comm.Freq.8kHz;

<sup>(2)</sup> 包含输入整流部分的损耗; / Including input rectifier losses;

<sup>(3)</sup> 为了使输出电流保持在额定, 电机零速时 PWM 频率会自动降低。 / PWM frequency will automatically decrease at zero speed, in order to keep nominal current output.

## 外形尺寸 Overall Dimensions



## 电机位置反馈选项 Motor Feedback Options

|  |   |
|--|---|
| 主编码器 (500kHz)<br>Main Encoder (500kHz) | 5 通道正弦编码器 (SinCos encoder), 2 个绝对值通道、2 个增量通道和 1 个零位通道<br>SinCos encoder 5 channels (2 absolute analog tracks/2 incremental analog tracks/index) |
|  | 增量编码器 (Incremental encoder), 1Vpp 或长线驱动<br>Incremental encoder (1 Vpp or Different Line Driver)   |
|  | 无传感器模式 (无电机位置反馈信号)<br>Sensorless algorithm (w/o feedback)   |
|  | EnDat 系列编码器, 支持 EnDat 1.0 - 2.2 协议 (系统默认编码器)<br>EnDat serial encoder 1.0 to 2.2 (default)   |
|  | 旋转变压器<br>Resolver   |
| 辅助编码器<br>Secondary Encoder             | Hiperface 系列编码器<br>Hiperface encoder  |
|  | 无换向信号通道的数字增量编码器 (500kHz)<br>Incremental digital encoder without commutation tracks (500kHz)   |
|  | EnDat 系列编码器<br>EnDat serial encoder   |

## 可编程信号输入 Programmable Inputs Signals

|  |  |
|--|--|
| 2 路差分 / 4 路单端模拟信号输入<br>2 differential / 4 single ended analog inputs | $\pm 10V$ (1mV) / $R_{in} = 10k\Omega$   |
| 8 路数字信号输入<br>8 digital inputs  | 20 - 30V / 对地 $R_{in} = 6.6k\Omega$<br>20 - 30V / $R_{in} = 6.6k\Omega$ to GND |
| 2 路隔离的模拟信号输入 (选配)<br>2 insulated analog inputs (optional)            | $\pm 10V$ (1mV)  |
| 8 路隔离的数字信号输入 (选配)<br>8 insulated analog inputs (optional)            | 5mA, 最大电压 24Vdc<br>5mA, 24Vdc max  |

## 可编程信号输出 Programmable Outputs Signals

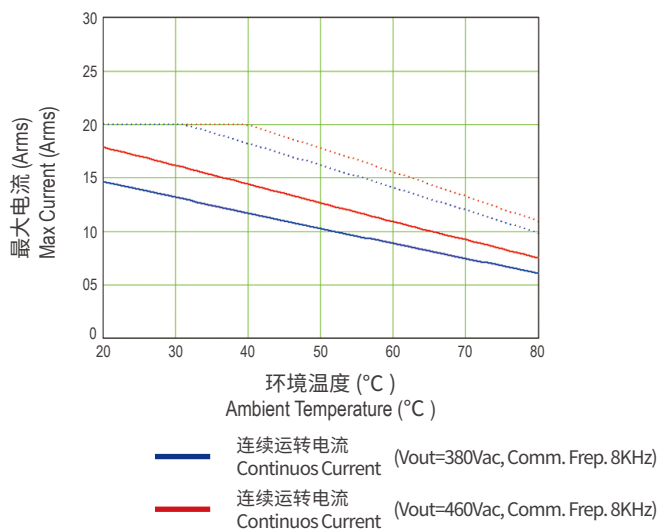
|   |   |
|---|---|
| 2 路模拟信号输出<br>2 analog outputs                               | 0-10V (1mV) FS (30mA)   |
| 4 路数字信号输出<br>4 digital outputs                              | PNP 集电极开路 24V (100mA)<br>PNP open collector 24V (100mA)   |
| 1 路继电器输出<br>1 watch dog relay                               | 2A / 30Vdc, 0.25A / 250Vac 常开 (N.O.) / 常闭 (N.C.) 针脚<br>2A / 30Vdc, 0.25A / 250Vac, NO/NC contacts |
| 2 路隔离的模拟信号输出 (选配)<br>2 insulated analog outputs (optional)  | $\pm 10V$ (1mV) FS (30mA)   |
| 2 路隔离的数字信号输出 (选配)<br>2 insulated digital outputs (optional) | 开关量, 9-28V / 2A<br>On.off switch, 9-28V / 2A  |

## 硬件配置 Hardware Configuration

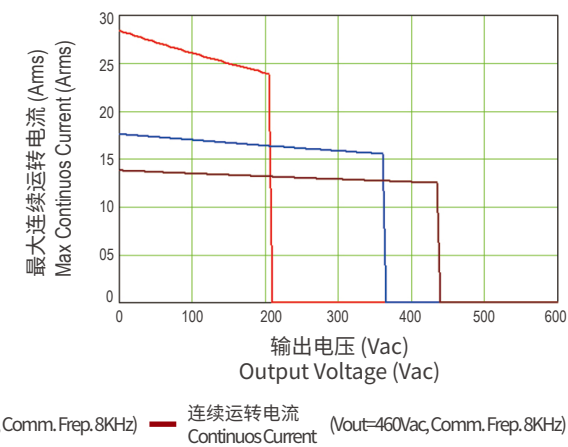
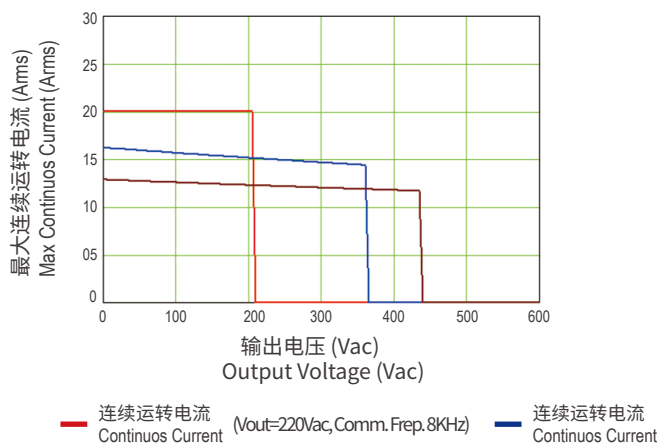
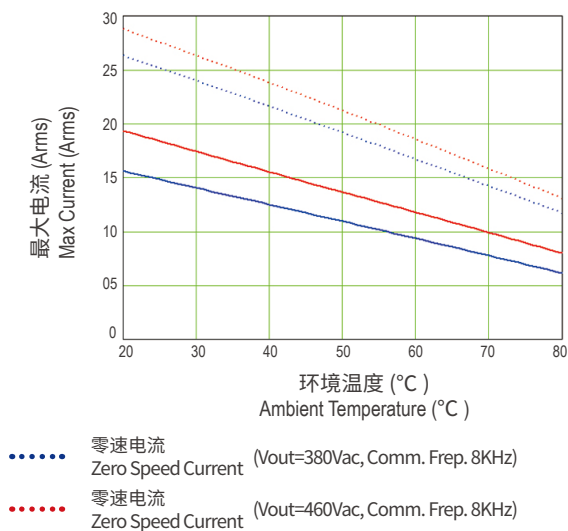
|  |  |   |
|--|--|---|
| 处理器<br>Processor Speed                 | 80MIPS $\mu$ C + FPGA / 120MIPS $\mu$ C + FPGA 增强版<br>80MIPS $\mu$ C + FPGA / 120MIPS $\mu$ C + FPGA Extreme Version | 可选<br>Optional  |
| 工作频率<br>Task Frequency                 | 电流环采样频率<br>Current / drive monitoring  | 1MHz  |
|  | 位置环 / 速度环频率<br>Position / speed loop   | 8kHz  |
|  | PLC 快速任务扫描频率<br>PLC fast task  | 8kHz  |
|  | PLC 慢速任务扫描频率<br>PLC slow task  | 15.625Hz to 1 kHz (可配置)<br>15.625 Hz to 1 kHz (user-programmable) |
| 位置模式可用<br>Position Loop Mode Available | 目标位置寄存器位宽<br>Target position register  | 32 or 64 bits   |
|  | 全数字 Id / Iq 控制<br>Full digital control Id/Iq   | 最高可达 16kHz<br>updated 16 kHz                                      |

# 驱动器运行区间 Drive Operational Area

## AxN 09.20.4



## AxN 16.60.4



# AxN Size 2

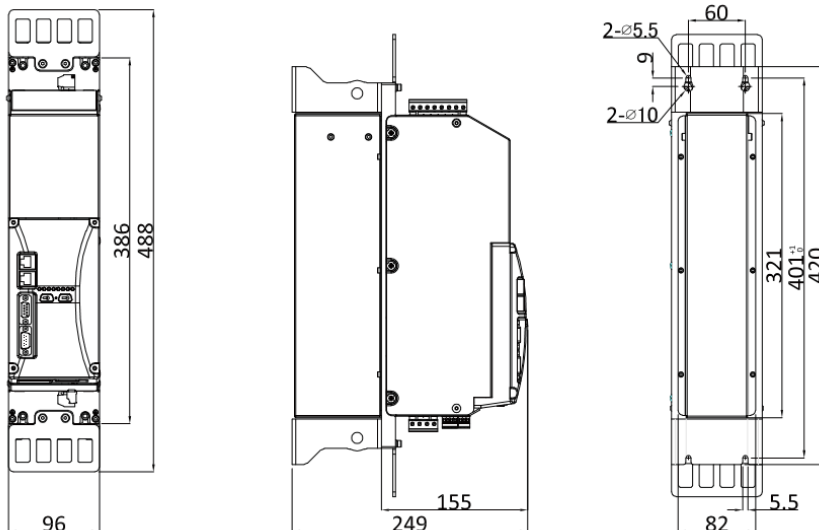
| 技术参数<br>Technical Specifications  | 符号<br>Symbol | AxN 15.30.4   | 单位<br>Units           |
|---|--------------|---|-----------------------|
| 主电源供电电压<br>Power Supply Voltage   | $V_{in}$     | 150 ~ 500   | Vac                   |
|   |              | 0 ~ 800   | Vdc                   |
| 辅助电源供电电压<br>Auxiliary Supply Voltage                                    | $V_{aux}$    | 24V $\pm$ 15% / 2A                                  | Vdc                   |
| 输出频率<br>Output Frequency  | f            | 0 ~ 1200  | Hz                    |
| 额定输出电流, $S1^{(1)}$<br>Current Output, $S1^{(1)}$                        | $I_n$        | 15  | Arms                  |
| 峰值输出电流 <sup>(1)</sup><br>Peak Current <sup>(1)</sup>                    | $I_p$        | 30  | Arms                  |
| 总功率损耗 <sup>(2)</sup><br>Power Losses Total <sup>(2)</sup>               | $P_l$        | 200   | W                     |
| 最大输出电压<br>Maximum Output Voltage  | $V_{out}$    | $V_{in} \times 0.95$                                | Vac                   |
| PWM 频率 <sup>(3)</sup><br>PWM Frequency <sup>(3)</sup>                   | $f_{pwm}$    | 4 / 8 / 16  | kHz                   |
| 额定输出功率时的效率 <sup>(1)</sup><br>Efficiency at Nominal Power <sup>(1)</sup> | ---          | 97.9  | %                     |
| 输入波形因数 (满负载)<br>Input form Factor(Full Load)                            | ---          | 0.9   | Vac                   |
| 最大制动电流<br>Maximum Braking Current                                       | ---          | 100% 峰值电流 ( $I_p$ )<br>100% of $I_p$ (Peak Current) | ---                   |
| 散热<br>Cooling   | ---          | 60 x 60 x32 风扇 x1<br>1 fan 60 x 60 x32              | ---                   |
| 风扇流量<br>Flow Rate   | ---          | 70  | m <sup>3</sup> / hour |
| 尺寸 (HxDxW)<br>Dimensions (HxDxW)  | ---          | 420 x 249 x 96                                      | mm                    |

<sup>(1)</sup> $V_{in}=380Vac$ ,  $V_{out}=V_{in} \times 0.95$ , 环境温度为 40°C, PWM 控制频率为 8kHz; /  $V_{in}=380Vac$ ,  $V_{out}=V_{in} \times 0.95$ ,  $T_{amb}=40^\circ C$ , Comm.Freq.8kHz;

<sup>(2)</sup> 包含输入整流部分的损耗; / Including input rectifier losses;

<sup>(3)</sup> 为了使输出电流保持在额定, 电机零速时 PWM 频率会自动降低。/ PWM frequency will automatically decrease at zero speed, in order to keep nominal current output.

## 外形尺寸 Overall Dimensions



## 电机位置反馈选项 Motor Feedback Options

|  |   |
|--|---|
| 主编码器 (500kHz)<br>Main Encoder (500kHz) | 5 通道正弦编码器 (SinCos encoder), 2 个绝对值通道、2 个增量通道和 1 个零位通道<br>SinCos encoder 5 channels (2 absolute analog tracks/2 incremental analog tracks/index) |
|  | 增量编码器 (Incremental encoder), 1Vpp 或长线驱动<br>Incremental encoder (1 Vpp or Different Line Driver)   |
|  | 无传感器模式 (无电机位置反馈信号)<br>Sensorless algorithm (w/o feedback)   |
|  | EnDat 系列编码器, 支持 EnDat 1.0 - 2.2 协议 (系统默认编码器)<br>EnDat serial encoder 1.0 to 2.2 (default)   |
|  | 旋转变压器<br>Resolver   |
| 辅助编码器<br>Secondary Encoder             | Hiperface 系列编码器<br>Hiperface encoder  |
|  | 无换向信号通道的数字增量编码器 (500kHz)<br>Incremental digital encoder without commutation tracks (500kHz)   |
|  | EnDat 系列编码器<br>EnDat serial encoder   |

## 可编程信号输入 Programmable Inputs Signals

|  |  |
|--|--|
| 2 路差分 / 4 路单端模拟信号输入<br>2 differential / 4 single ended analog inputs | $\pm 10V$ (1mV) / $R_{in} = 10k\Omega$   |
| 8 路数字信号输入<br>8 digital inputs  | 20 - 30V / 对地 $R_{in} = 6.6k\Omega$<br>20 - 30V / $R_{in} = 6.6k\Omega$ to GND |
| 2 路隔离的模拟信号输入 (选配)<br>2 insulated analog inputs (optional)            | $\pm 10V$ (1mV)  |
| 8 路隔离的数字信号输入 (选配)<br>8 insulated analog inputs (optional)            | 5mA, 最大电压 24Vdc<br>5mA, 24Vdc max  |

## 可编程信号输出 Programmable Outputs Signals

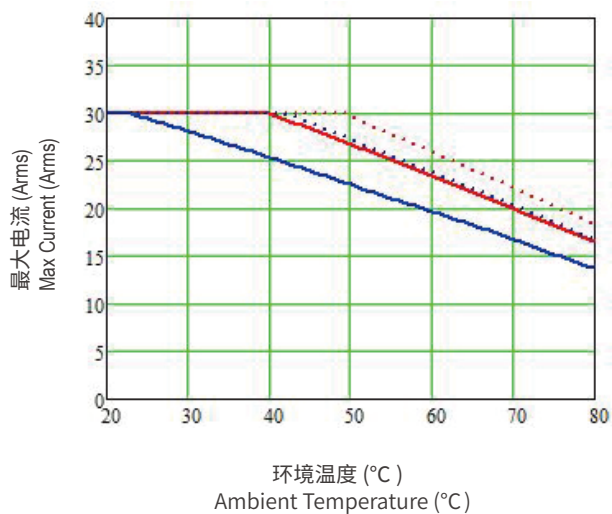
|   |   |
|---|---|
| 2 路模拟信号输出<br>2 analog outputs                               | 0-10V (1mV) FS (30mA)   |
| 4 路数字信号输出<br>4 digital outputs                              | PNP 集电极开路 24V (100mA)<br>PNP open collector 24V (100mA)   |
| 1 路继电器输出<br>1 watch dog relay                               | 2A / 30Vdc, 0.25A / 250Vac 常开 (N.O.) / 常闭 (N.C.) 针脚<br>2A / 30Vdc, 0.25A / 250Vac, NO/NC contacts |
| 2 路隔离的模拟信号输出 (选配)<br>2 insulated analog outputs (optional)  | $\pm 10V$ (1mV) FS (30mA)   |
| 2 路隔离的数字信号输出 (选配)<br>2 insulated digital outputs (optional) | 开关量, 9-28V / 2A<br>On.off switch, 9-28V / 2A  |

## 硬件配置 Hardware Configuration

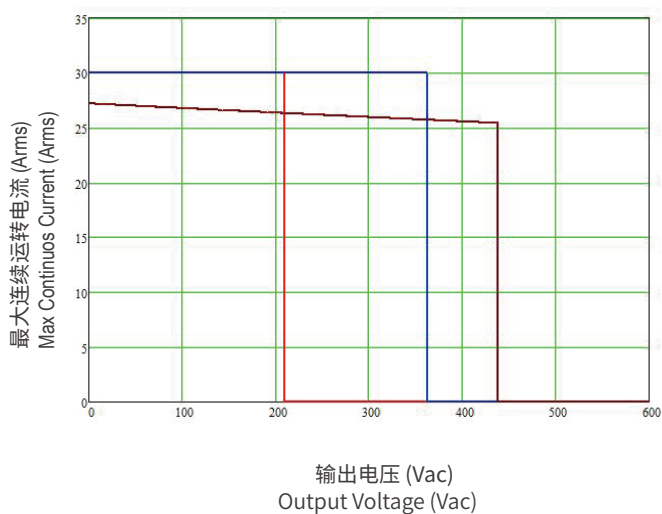
|  |  |   |
|--|--|---|
| 处理器<br>Processor Speed                 | 80MIPS $\mu$ C + FPGA / 120MIPS $\mu$ C + FPGA 增强版<br>80MIPS $\mu$ C + FPGA / 120MIPS $\mu$ C + FPGA Extreme Version | 可选<br>Optional  |
| 工作频率<br>Task Frequency                 | 电流环采样频率<br>Current / drive monitoring  | 1MHz  |
|  | 位置环 / 速度环频率<br>Position / speed loop   | 8kHz  |
|  | PLC 快速任务扫描频率<br>PLC fast task  | 8kHz  |
|  | PLC 慢速任务扫描频率<br>PLC slow task  | 15.625Hz to 1 kHz (可配置)<br>15.625 Hz to 1 kHz (user-programmable) |
| 位置模式可用<br>Position Loop Mode Available | 目标位置寄存器位宽<br>Target position register  | 32 or 64 bits   |
|  | 全数字 Id / Iq 控制<br>Full digital control Id/Iq   | 最高可达 16kHz<br>updated 16 kHz                                      |

# 驱动器运行区间 Drive Operational Area

AxN 15.30.4



- 连续运转电流 (Vout=380Vac, Comm. Freq. 8KHz)  
Continuous Current
- 连续运转电流 (Vout=460Vac, Comm. Freq. 8KHz)  
Continuous Current
- ..... 零速电流 (Vout=380Vac, Comm. Freq. 8KHz)  
Zero Speed Current
- ..... 零速电流 (Vout=460Vac, Comm. Freq. 8KHz)  
Zero Speed Current



- 连续运转电流 (Vout=220Vac, Comm. Freq. 8KHz)  
Continuous Current
- 连续运转电流 (Vout=380Vac, Comm. Freq. 8KHz)  
Continuous Current
- 连续运转电流 (Vout=460Vac, Comm. Freq. 8KHz)  
Continuous Current



# AxN Size 3

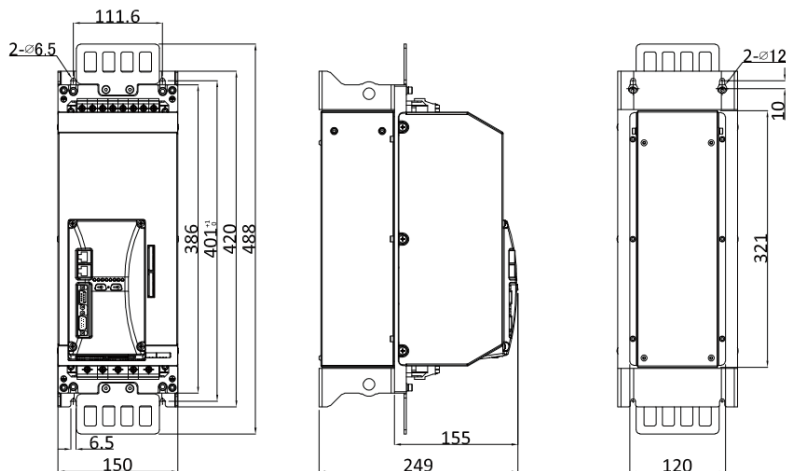
| 技术参数<br>Technical Specifications  | 符号<br>Symbol | AxN 22.44.4   | AxN 35.70.4 | AxN 50.100.4 | 单位<br>Units           |
|---|--------------|---|-------------|--------------|-----------------------|
| 主电源供电电压<br>Power Supply Voltage   | $V_{in}$     | 150 ~ 500   |             |              | Vac                   |
|   |              | 0 ~ 800   |             |              | Vdc                   |
| 辅助电源供电电压<br>Auxiliary Supply Voltage                                    | $V_{aux}$    | 24V $\pm$ 15% / 3A                                  |             |              | Vdc                   |
| 输出频率<br>Output Frequency  | f            | 0 ~ 1200  |             |              | Hz                    |
| 额定输出电流, $S1^{(1)}$<br>Current Output, $S1^{(1)}$                        | $I_n$        | 22  | 35          | 50           | Arms                  |
| 峰值输出电流 <sup>(1)</sup><br>Peak Current <sup>(1)</sup>                    | $I_p$        | 44  | 70          | 100          | Arms                  |
| 总功率损耗 <sup>(2)</sup><br>Power Losses Total <sup>(2)</sup>               | $P_l$        | 280   | 400         | 590          | W                     |
| 最大输出电压<br>Maximum Output Voltage  | $V_{out}$    | $V_{in} \times 0.95$                                |             |              | Vac                   |
| PWM 频率 <sup>(3)</sup><br>PWM Frequency <sup>(3)</sup>                   | $fpw_m$      | 4 / 8 / 16  |             |              | kHz                   |
| 额定输出功率时的效率 <sup>(1)</sup><br>Efficiency at Nominal Power <sup>(1)</sup> | ---          | 98  | 98.2        | 98.1         | %                     |
| 输入波形因数 (满负载)<br>Input form Factor(Full Load)                            | ---          | 0.9   |             |              | Vac                   |
| 最大制动电流<br>Maximum Braking Current                                       | ---          | 100% 峰值电流 ( $I_p$ )<br>100% of $I_p$ (Peak Current) |             |              | ---                   |
| 散热<br>Cooling   | ---          | 80 x 80 x38 可调速风扇 x1<br>1 PWM fan 80 x 80 x38       |             |              | ---                   |
| 风扇流量<br>Flow Rate   | ---          | 136   |             |              | m <sup>3</sup> / hour |
| 尺寸 (HxDxW)<br>Dimensions (HxDxW)  | ---          | 488 x 249 x 150                                     |             |              | mm                    |

<sup>(1)</sup> $V_{in}=380Vac$ ,  $V_{out}=V_{in} \times 0.95$ , 环境温度为 40°C, PWM 控制频率为 8kHz; /  $V_{in}=380Vac$ ,  $V_{out}=V_{in} \times 0.95$ ,  $T_{amb}=40^\circ C$ , Comm.Freq.8kHz;

<sup>(2)</sup> 包含输入整流部分的损耗; / Including input rectifier losses;

<sup>(3)</sup> 为了使输出电流保持在额定, 电机零速时 PWM 频率会自动降低。/ PWM frequency will automatically decrease at zero speed, in order to keep nominal current output.

## 外形尺寸 Overall Dimensions



## 电机位置反馈选项 Motor Feedback Options

|  |   |
|--|---|
| 主编码器 (500kHz)<br>Main Encoder (500kHz) | 5 通道正弦编码器 (SinCos encoder), 2 个绝对值通道、2 个增量通道和 1 个零位通道<br>SinCos encoder 5 channels (2 absolute analog tracks/2 incremental analog tracks/index) |
|  | 增量编码器 (Incremental encoder), 1Vpp 或长线驱动<br>Incremental encoder (1 Vpp or Different Line Driver)   |
|  | 无传感器模式 (无电机位置反馈信号)<br>Sensorless algorithm (w/o feedback)   |
|  | EnDat 系列编码器, 支持 EnDat 1.0 - 2.2 协议 (系统默认编码器)<br>EnDat serial encoder 1.0 to 2.2 (default)   |
|  | 旋转变压器<br>Resolver   |
| 辅助编码器<br>Secondary Encoder             | Hiperface 系列编码器<br>Hiperface encoder  |
|  | 无换向信号通道的数字增量编码器 (500kHz)<br>Incremental digital encoder without commutation tracks (500kHz)   |
|  | EnDat 系列编码器<br>EnDat serial encoder   |

## 可编程信号输入 Programmable Inputs Signals

|  |  |
|--|--|
| 2 路差分 / 4 路单端模拟信号输入<br>2 differential / 4 single ended analog inputs | $\pm 10V$ (1mV) / $R_{in} = 10k\Omega$   |
| 8 路数字信号输入<br>8 digital inputs  | 20 - 30V / 对地 $R_{in} = 6.6k\Omega$<br>20 - 30V / $R_{in} = 6.6k\Omega$ to GND |
| 2 路隔离的模拟信号输入 (选配)<br>2 insulated analog inputs (optional)            | $\pm 10V$ (1mV)  |
| 8 路隔离的数字信号输入 (选配)<br>8 insulated analog inputs (optional)            | 5mA, 最大电压 24Vdc<br>5mA, 24Vdc max  |

## 可编程信号输出 Programmable Outputs Signals

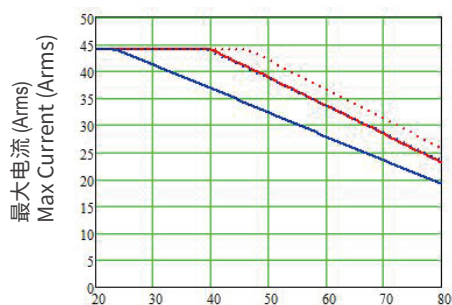
|   |   |
|---|---|
| 2 路模拟信号输出<br>2 analog outputs                               | 0-10V (1mV) FS (30mA)   |
| 4 路数字信号输出<br>4 digital outputs                              | PNP 集电极开路 24V (100mA)<br>PNP open collector 24V (100mA)   |
| 1 路继电器输出<br>1 watch dog relay                               | 2A / 30Vdc, 0.25A / 250Vac 常开 (N.O.) / 常闭 (N.C.) 针脚<br>2A / 30Vdc, 0.25A / 250Vac, NO/NC contacts |
| 2 路隔离的模拟信号输出 (选配)<br>2 insulated analog outputs (optional)  | $\pm 10V$ (1mV) FS (30mA)   |
| 2 路隔离的数字信号输出 (选配)<br>2 insulated digital outputs (optional) | 开关量, 9-28V / 2A<br>On.off switch, 9-28V / 2A  |

## 硬件配置 Hardware Configuration

|  |  |   |
|--|--|---|
| 处理器<br>Processor Speed                 | 80MIPS $\mu$ C + FPGA / 120MIPS $\mu$ C + FPGA 增强版<br>80MIPS $\mu$ C + FPGA / 120MIPS $\mu$ C + FPGA Extreme Version | 可选<br>Optional  |
| 工作频率<br>Task Frequency                 | 电流环采样频率<br>Current / drive monitoring  | 1MHz  |
|  | 位置环 / 速度环频率<br>Position / speed loop   | 8kHz  |
|  | PLC 快速任务扫描频率<br>PLC fast task  | 8kHz  |
|  | PLC 慢速任务扫描频率<br>PLC slow task  | 15.625Hz to 1 kHz (可配置)<br>15.625 Hz to 1 kHz (user-programmable) |
| 位置模式可用<br>Position Loop Mode Available | 目标位置寄存器位宽<br>Target position register  | 32 or 64 bits   |
|  | 全数字 Id / Iq 控制<br>Full digital control Id/Iq   | 最高可达 16kHz<br>updated 16 kHz                                      |

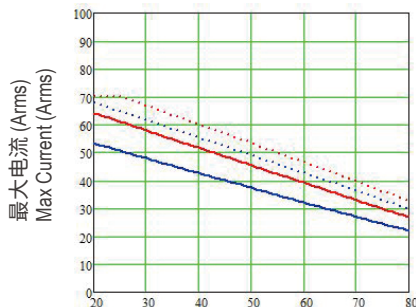
# 驱动器运行区间 Drive Operational Area

## AxN 22.44.4



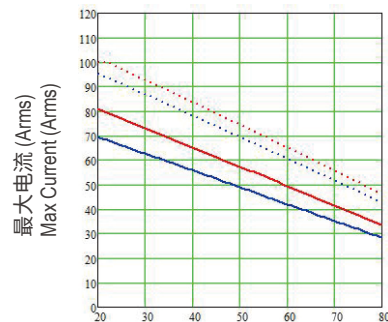
环境温度 (°C)  
Ambient Temperature (°C)

## AxN 35.70.4



环境温度 (°C)  
Ambient Temperature (°C)

## AxN 50.100.4



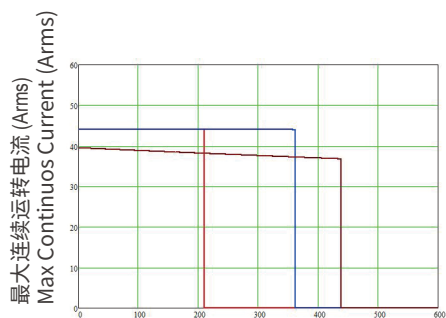
环境温度 (°C)  
Ambient Temperature (°C)

— 连续运转电流  
Continuous Current (Vout=380Vac, Comm. Freq. 8KHz)

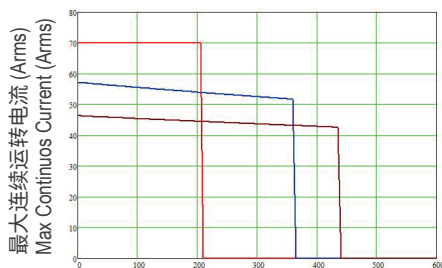
— 连续运转电流  
Continuous Current (Vout=460Vac, Comm. Freq. 8KHz)

..... 零速电流  
Zero Speed Current (Vout=380Vac, Comm. Freq. 8KHz)

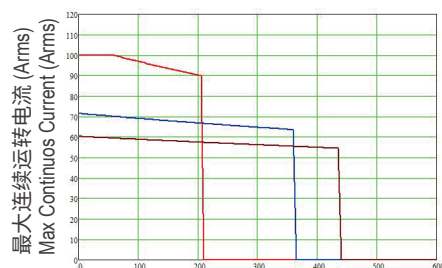
..... 零速电流  
Zero Speed Current (Vout=460Vac, Comm. Freq. 8KHz)



输出电压 (Vac)  
Output Voltage (Vac)



输出电压 (Vac)  
Output Voltage (Vac)



输出电压 (Vac)  
Output Voltage (Vac)

— 连续运转电流  
Continuous Current (Vout=220Vac, Comm. Freq. 8KHz)

— 连续运转电流  
Continuous Current (Vout=380Vac, Comm. Freq. 8KHz)

— 连续运转电流  
Continuous Current (Vout=460Vac, Comm. Freq. 8KHz)



# AxN Size 4

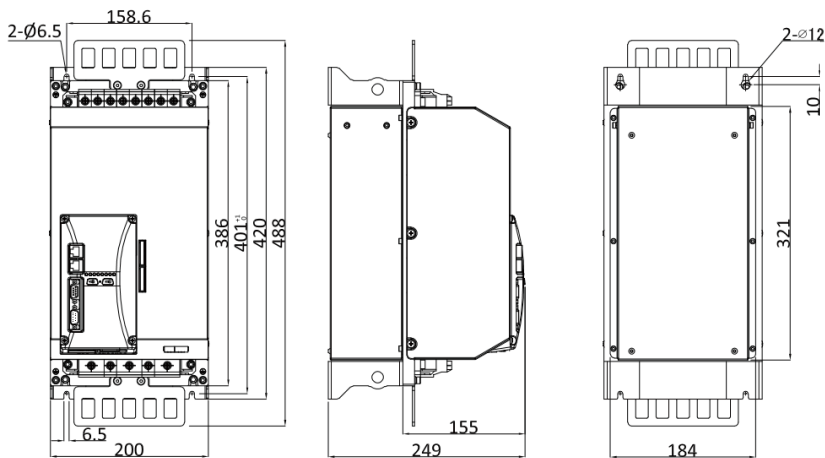
| 技术参数<br>Technical Specifications  | 符号<br>Symbol | AxN 70.140.4  | 单位<br>Units           |
|---|--------------|---|-----------------------|
| 主电源供电电压<br>Power Supply Voltage   | $V_{in}$     | 150 ~ 500   | Vac                   |
|   |              | 0 ~ 800   | Vdc                   |
| 辅助电源供电电压<br>Auxiliary Supply Voltage                                    | $V_{aux}$    | 24V $\pm$ 15% / 2A                                  | Vdc                   |
| 输出频率<br>Output Frequency  | f            | 0 ~ 1200  | Hz                    |
| 额定输出电流, $S1^{(1)}$<br>Current Output, $S1^{(1)}$                        | $I_n$        | 70  | Arms                  |
| 峰值输出电流 <sup>(1)</sup><br>Peak Current <sup>(1)</sup>                    | $I_p$        | 140   | Arms                  |
| 总功率损耗 <sup>(2)</sup><br>Power Losses Total <sup>(2)</sup>               | $P_l$        | 870   | W                     |
| 最大输出电压<br>Maximum Output Voltage  | $V_{out}$    | $V_{in} \times 0.95$                                | Vac                   |
| PWM 频率 <sup>(3)</sup><br>PWM Frequency <sup>(3)</sup>                   | $f_{PWM}$    | 4 / 8 / 16  | kHz                   |
| 额定输出功率时的效率 <sup>(1)</sup><br>Efficiency at Nominal Power <sup>(1)</sup> | ---          | 98.1  | %                     |
| 输入波形因数 (满负载)<br>Input form Factor(Full Load)                            | ---          | 0.9   | Vac                   |
| 最大制动电流<br>Maximum Braking Current                                       | ---          | 100% 峰值电流 ( $I_p$ )<br>100% of $I_p$ (Peak Current) | ---                   |
| 散热<br>Cooling   | ---          | 80 x 80 x 38 可调速风扇 x2<br>2 PWM fan 80 x 80 x 38     | ---                   |
| 风扇流量<br>Flow Rate   | ---          | 110 x 2   | m <sup>3</sup> / hour |
| 尺寸 (HxDxW)<br>Dimensions (HxDxW)  | ---          | 420 x 249 x 200                                     | mm                    |

<sup>(1)</sup> $V_{in}=380Vac$ ,  $V_{out}=V_{in} \times 0.95$ , 环境温度为 40°C, PWM 控制频率为 8kHz; /  $V_{in}=380Vac$ ,  $V_{out}=V_{in} \times 0.95$ ,  $T_{amb}=40^\circ C$ , Comm.Freq.8kHz;

<sup>(2)</sup> 包含输入整流部分的损耗; / Including input rectifier losses;

<sup>(3)</sup> 为了使输出电流保持在额定, 电机零速时 PWM 频率会自动降低。 / PWM frequency will automatically decrease at zero speed, in order to keep nominal current output.

## 外形尺寸 Overall Dimensions



## 电机位置反馈选项 Motor Feedback Options

|  |   |
|--|---|
| 主编码器 (500kHz)<br>Main Encoder (500kHz) | 5 通道正弦编码器 (SinCos encoder), 2 个绝对值通道、2 个增量通道和 1 个零位通道<br>SinCos encoder 5 channels (2 absolute analog tracks/2 incremental analog tracks/index) |
|  | 增量编码器 (Incremental encoder), 1Vpp 或长线驱动<br>Incremental encoder (1 Vpp or Different Line Driver)   |
|  | 无传感器模式 (无电机位置反馈信号)<br>Sensorless algorithm (w/o feedback)   |
|  | EnDat 系列编码器, 支持 EnDat 1.0 - 2.2 协议 (系统默认编码器)<br>EnDat serial encoder 1.0 to 2.2 (default)   |
|  | 旋转变压器<br>Resolver   |
| 辅助编码器<br>Secondary Encoder             | Hiperface 系列编码器<br>Hiperface encoder  |
|  | 无换向信号通道的数字增量编码器 (500kHz)<br>Incremental digital encoder without commutation tracks (500kHz)   |
|  | EnDat 系列编码器<br>EnDat serial encoder   |

## 可编程信号输入 Programmable Inputs Signals

|  |  |
|--|--|
| 2 路差分 / 4 路单端模拟信号输入<br>2 differential / 4 single ended analog inputs | $\pm 10V$ (1mV) / $R_{in} = 10k\Omega$   |
| 8 路数字信号输入<br>8 digital inputs  | 20 - 30V / 对地 $R_{in} = 6.6k\Omega$<br>20 - 30V / $R_{in} = 6.6k\Omega$ to GND |
| 2 路隔离的模拟信号输入 (选配)<br>2 insulated analog inputs (optional)            | $\pm 10V$ (1mV)  |
| 8 路隔离的数字信号输入 (选配)<br>8 insulated analog inputs (optional)            | 5mA, 最大电压 24Vdc<br>5mA, 24Vdc max  |

## 可编程信号输出 Programmable Outputs Signals

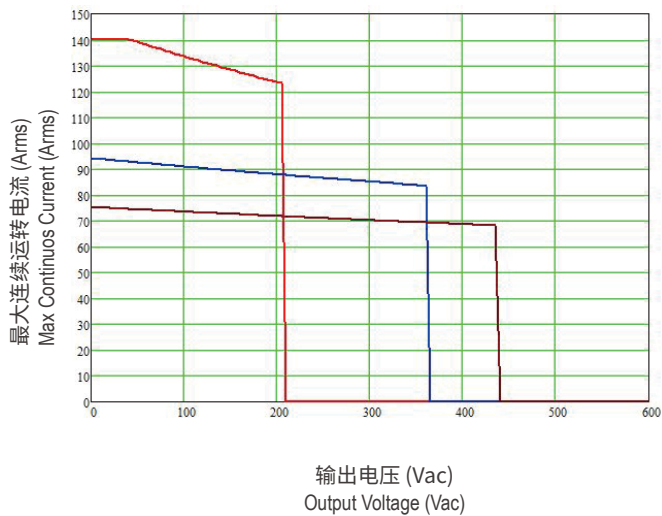
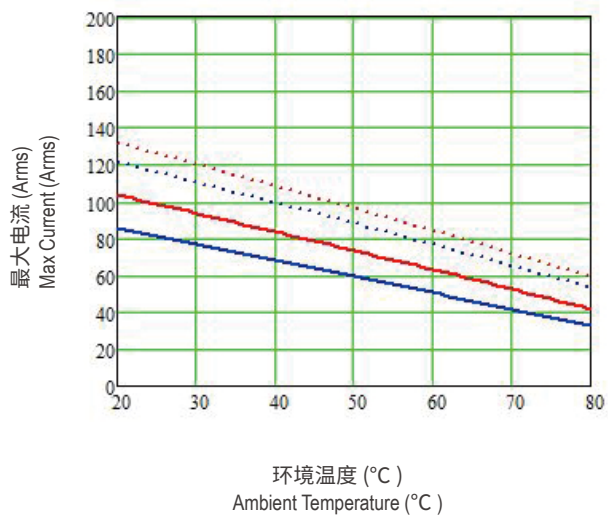
|   |   |
|---|---|
| 2 路模拟信号输出<br>2 analog outputs                               | 0-10V (1mV) FS (30mA)   |
| 4 路数字信号输出<br>4 digital outputs                              | PNP 集电极开路 24V (100mA)<br>PNP open collector 24V (100mA)   |
| 1 路继电器输出<br>1 watch dog relay                               | 2A / 30Vdc, 0.25A / 250Vac 常开 (N.O.) / 常闭 (N.C.) 针脚<br>2A / 30Vdc, 0.25A / 250Vac, NO/NC contacts |
| 2 路隔离的模拟信号输出 (选配)<br>2 insulated analog outputs (optional)  | $\pm 10V$ (1mV) FS (30mA)   |
| 2 路隔离的数字信号输出 (选配)<br>2 insulated digital outputs (optional) | 开关量, 9-28V / 2A<br>On.off switch, 9-28V / 2A  |

## 硬件配置 Hardware Configuration

|  |  |   |
|--|--|---|
| 处理器<br>Processor Speed                 | 80MIPS $\mu$ C + FPGA / 120MIPS $\mu$ C + FPGA 增强版<br>80MIPS $\mu$ C + FPGA / 120MIPS $\mu$ C + FPGA Extreme Version | 可选<br>Optional  |
| 工作频率<br>Task Frequency                 | 电流环采样频率<br>Current / drive monitoring  | 1MHz  |
|  | 位置环 / 速度环频率<br>Position / speed loop   | 8kHz  |
|  | PLC 快速任务扫描频率<br>PLC fast task  | 8kHz  |
|  | PLC 慢速任务扫描频率<br>PLC slow task  | 15.625Hz to 1 kHz (可配置)<br>15.625 Hz to 1 kHz (user-programmable) |
| 位置模式可用<br>Position Loop Mode Available | 目标位置寄存器位宽<br>Target position register  | 32 or 64 bits   |
|  | 全数字 Id / Iq 控制<br>Full digital control Id/Iq   | 最高可达 16kHz<br>updated 16 kHz                                      |

# 驱动器运行区间 Drive Operational Area

AxN 70.140.4



- 连续运转电流 (Vout=380Vac, Comm. Freq. 8KHz)  
Continuous Current (Vout=380Vac, Comm. Freq. 8KHz)
- 连续运转电流 (Vout=460Vac, Comm. Freq. 8KHz)  
Continuous Current (Vout=460Vac, Comm. Freq. 8KHz)
- ..... 零速电流 (Vout=380Vac, Comm. Freq. 8KHz)  
Zero Speed Current (Vout=380Vac, Comm. Freq. 8KHz)
- ..... 零速电流 (Vout=460Vac, Comm. Freq. 8KHz)  
Zero Speed Current (Vout=460Vac, Comm. Freq. 8KHz)

- 连续运转电流 (Vout=220Vac, Comm. Freq. 8KHz)  
Continuous Current (Vout=220Vac, Comm. Freq. 8KHz)
- 连续运转电流 (Vout=380Vac, Comm. Freq. 8KHz)  
Continuous Current (Vout=380Vac, Comm. Freq. 8KHz)
- 连续运转电流 (Vout=460Vac, Comm. Freq. 8KHz)  
Continuous Current (Vout=460Vac, Comm. Freq. 8KHz)



# AxN Size 5

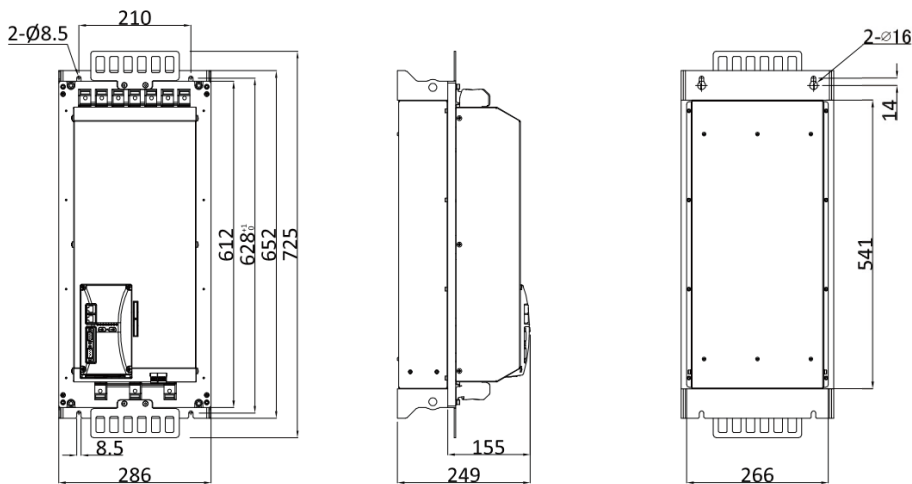
| 技术参数<br>Technical Specifications  | 符号<br>Symbol     | AxN 90.150.4  | AxN 110.200.4 | AxN 110.250.4 | AxN 150.300.4 | 单位<br>Units           |
|---|------------------|---|---------------|---------------|---------------|-----------------------|
| 主电源供电电压<br>Power Supply Voltage   | $V_{in}$         | 150 ~ 500   |               |               |               | Vac                   |
|   |                  | 0 ~ 800   |               |               |               | Vdc                   |
| 辅助电源供电电压<br>Auxiliary Supply Voltage                                    | $V_{aux}$        | 24V ± 15% / 3A                                      |               |               |               | Vdc                   |
| 输出频率<br>Output Frequency  | f                | 0 ~ 1200  |               |               |               | Hz                    |
| 额定输出电流, $S1^{(1)}$<br>Current Output, $S1^{(1)}$                        | $I_n$            | 90  | 110           | 110           | 150           | Arms                  |
| 峰值输出电流 <sup>(1)</sup><br>Peak Current <sup>(1)</sup>                    | $I_p$            | 150   | 200           | 250           | 300           | Arms                  |
| 总功率损耗 <sup>(2)</sup><br>Power Losses Total <sup>(2)</sup>               | $P_l$            | 1050  | 1280          | 1300          | 1772          | W                     |
| 最大输出电压<br>Maximum Output Voltage  | $V_{out}$        | $V_{in} \times 0.95$                                |               |               |               | Vac                   |
| PWM 频率 <sup>(3)</sup><br>PWM Frequency <sup>(3)</sup>                   | fpw <sub>m</sub> | 4 / 8 / 16  |               |               |               | kHz                   |
| 额定输出功率时的效率 <sup>(1)</sup><br>Efficiency at Nominal Power <sup>(1)</sup> | ---              | 98.2  | 98.2          | 97.1          | 97.1          | %                     |
| 输入波形因数 (满负载)<br>Input form Factor(Full Load)                            | ---              | 0.9   |               |               |               | Vac                   |
| 最大制动电流<br>Maximum Braking Current                                       | ---              | 100% 峰值电流 ( $I_p$ )<br>100% of $I_p$ (Peak Current) |               |               |               | ---                   |
| 散热<br>Cooling   | ---              | 80 x 80 x38 可调速风扇 x3<br>3 PWM fan 80 x 80 x38       |               |               |               | ---                   |
| 风扇流量<br>Flow Rate   | ---              | 110 x3  |               |               |               | m <sup>3</sup> / hour |
| 尺寸 (HxDxW)<br>Dimensions (HxDxW)  | ---              | 725 x 249 x 286                                     |               |               |               | mm                    |

<sup>(1)</sup> $V_{in}=380Vac$ ,  $V_{out}=V_{in} \times 0.95$ , 环境温度为 40°C, PWM 控制频率为 8kHz; /  $V_{in}=380Vac$ ,  $V_{out}=V_{in} \times 0.95$ ,  $T_{amb}=40^{\circ}C$ , Comm.Freq.8kHz;

<sup>(2)</sup> 包含输入整流部分的损耗; / Including input rectifier losses;

<sup>(3)</sup> 为了使输出电流保持在额定, 电机零速时 PWM 频率会自动降低。 / PWM frequency will automatically decrease at zero speed, in order to keep nominal current output.

## 外形尺寸 Overall Dimensions



## 电机位置反馈选项 Motor Feedback Options

|  |   |
|--|---|
| 主编码器 (500kHz)<br>Main Encoder (500kHz) | 5 通道正弦编码器 (SinCos encoder), 2 个绝对值通道、2 个增量通道和 1 个零位通道<br>SinCos encoder 5 channels (2 absolute analog tracks/2 incremental analog tracks/index) |
|  | 增量编码器 (Incremental encoder), 1Vpp 或长线驱动<br>Incremental encoder (1 Vpp or Different Line Driver)   |
|  | 无传感器模式 (无电机位置反馈信号)<br>Sensorless algorithm (w/o feedback)   |
|  | EnDat 系列编码器, 支持 EnDat 1.0 - 2.2 协议 (系统默认编码器)<br>EnDat serial encoder 1.0 to 2.2 (default)   |
|  | 旋转变压器<br>Resolver   |
| 辅助编码器<br>Secondary Encoder             | Hiperface 系列编码器<br>Hiperface encoder  |
|  | 无换向信号通道的数字增量编码器 (500kHz)<br>Incremental digital encoder without commutation tracks (500kHz)   |
|  | EnDat 系列编码器<br>EnDat serial encoder   |

## 可编程信号输入 Programmable Inputs Signals

|  |  |
|--|--|
| 2 路差分 / 4 路单端模拟信号输入<br>2 differential / 4 single ended analog inputs | $\pm 10V$ (1mV) / $R_{in} = 10k\Omega$   |
| 8 路数字信号输入<br>8 digital inputs  | 20 - 30V / 对地 $R_{in} = 6.6k\Omega$<br>20 - 30V / $R_{in} = 6.6k\Omega$ to GND |
| 2 路隔离的模拟信号输入 (选配)<br>2 insulated analog inputs (optional)            | $\pm 10V$ (1mV)  |
| 8 路隔离的数字信号输入 (选配)<br>8 insulated analog inputs (optional)            | 5mA, 最大电压 24Vdc<br>5mA, 24Vdc max  |

## 可编程信号输出 Programmable Outputs Signals

|   |   |
|---|---|
| 2 路模拟信号输出<br>2 analog outputs                               | 0-10V (1mV) FS (30mA)   |
| 4 路数字信号输出<br>4 digital outputs                              | PNP 集电极开路 24V (100mA)<br>PNP open collector 24V (100mA)   |
| 1 路继电器输出<br>1 watch dog relay                               | 2A / 30Vdc, 0.25A / 250Vac 常开 (N.O.) / 常闭 (N.C.) 针脚<br>2A / 30Vdc, 0.25A / 250Vac, NO/NC contacts |
| 2 路隔离的模拟信号输出 (选配)<br>2 insulated analog outputs (optional)  | $\pm 10V$ (1mV) FS (30mA)   |
| 2 路隔离的数字信号输出 (选配)<br>2 insulated digital outputs (optional) | 开关量, 9-28V / 2A<br>On.off switch, 9-28V / 2A  |

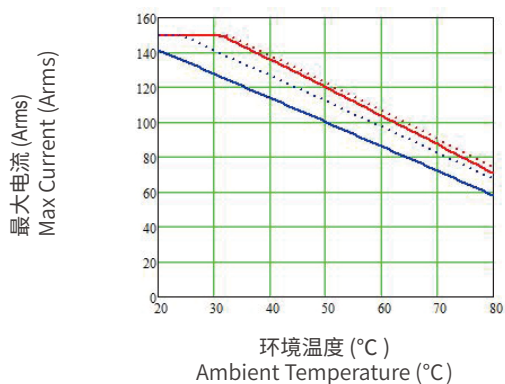
## 硬件配置 Hardware Configuration

|  |  |   |
|--|--|---|
| 处理器<br>Processor Speed                 | 80MIPS $\mu$ C + FPGA / 120MIPS $\mu$ C + FPGA 增强版<br>80MIPS $\mu$ C + FPGA / 120MIPS $\mu$ C + FPGA Extreme Version | 可选<br>Optional  |
| 工作频率<br>Task Frequency                 | 电流环采样频率<br>Current / drive monitoring  | 1MHz  |
|  | 位置环 / 速度环频率<br>Position / speed loop   | 8kHz  |
|  | PLC 快速任务扫描频率<br>PLC fast task  | 8kHz  |
|  | PLC 慢速任务扫描频率<br>PLC slow task  | 15.625Hz to 1 kHz (可配置)<br>15.625 Hz to 1 kHz (user-programmable) |
| 位置模式可用<br>Position Loop Mode Available | 目标位置寄存器位宽<br>Target position register  | 32 or 64 bits   |
|  | 全数字 Id / Iq 控制<br>Full digital control Id/Iq   | 最高可达 16kHz<br>updated 16 kHz                                      |



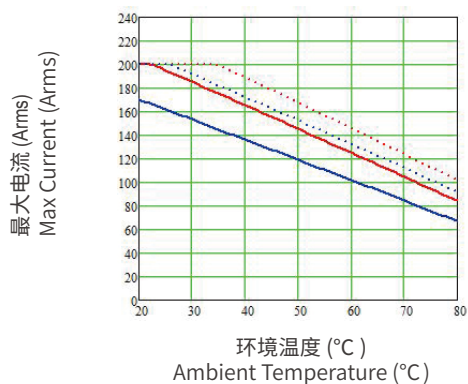
# 驱动器运行区间 Drive Operational Area

## AxN 90.150.4

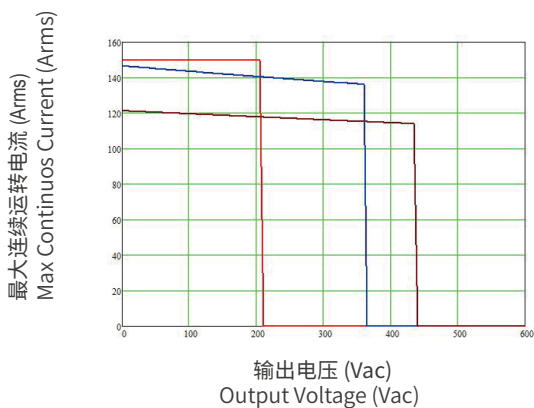


— 连续运转电流 (Vout=380Vac, Comm. Freq. 8KHz)  
 Continuos Current  
— 连续运转电流 (Vout=460Vac, Comm. Freq. 8KHz)  
 Continuos Current

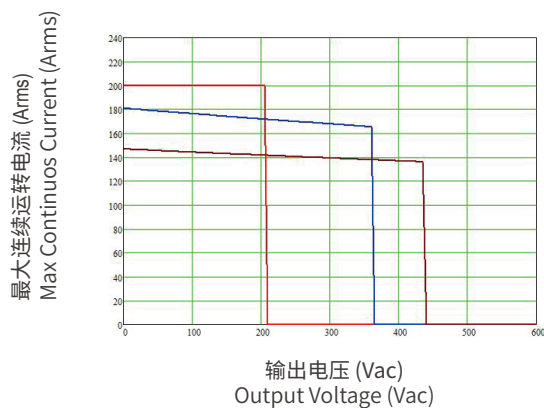
## AxN 110.200.4



— 连续运转电流 (Vout=380Vac, Comm. Freq. 8KHz)  
 Continuos Current  
— 连续运转电流 (Vout=460Vac, Comm. Freq. 8KHz)  
 Continuos Current  
····· 零速电流 (Vout=380Vac, Comm. Freq. 8KHz)  
 Zero Speed Current  
····· 零速电流 (Vout=460Vac, Comm. Freq. 8KHz)  
 Zero Speed Current



— 连续运转电流 (Vout=220Vac, Comm. Freq. 8KHz)  
 Continuos Current  
— 连续运转电流 (Vout=380Vac, Comm. Freq. 8KHz)  
 Continuos Current



— 连续运转电流 (Vout=460Vac, Comm. Freq. 8KHz)  
 Continuos Current

# AxN Size 6

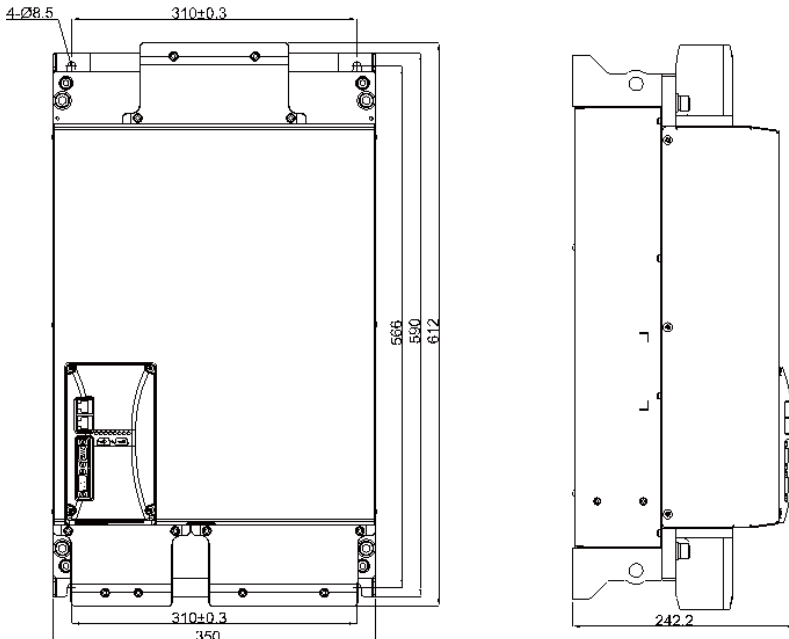
| 技术参数<br>Technical Specifications  | 符号<br>Symbol | AxN 200.400.4                                       | 单位<br>Units           |
|---|--------------|---|-----------------------|
| 主电源供电电压<br>Power Supply Voltage   | $V_{in}$     | 150 ~ 500   | Vac                   |
|   |              | 0 ~ 800   | Vdc                   |
| 辅助电源供电电压<br>Auxiliary Supply Voltage                                    | $V_{aux}$    | 24V $\pm$ 15% / 8A                                  | Vdc                   |
| 输出频率<br>Output Frequency  | f            | 0 ~ 1200  | Hz                    |
| 额定输出电流, $S1^{(1)}$<br>Current Output, $S1^{(1)}$                        | $I_n$        | 200   | Arms                  |
| 峰值输出电流 <sup>(1)</sup><br>Peak Current <sup>(1)</sup>                    | $I_p$        | 400   | Arms                  |
| 总功率损耗 <sup>(2)</sup><br>Power Losses Total <sup>(2)</sup>               | $P_l$        | 3280  | W                     |
| 最大输出电压<br>Maximum Output Voltage  | $V_{out}$    | $V_{in} \times 0.95$                                | Vac                   |
| PWM 频率 <sup>(3)</sup><br>PWM Frequency <sup>(3)</sup>                   | $fpw_m$      | 4 / 8 / 16  | kHz                   |
| 额定输出功率时的效率 <sup>(1)</sup><br>Efficiency at Nominal Power <sup>(1)</sup> | ---          | 97.1  | %                     |
| 输入波形因数 (满载)<br>Input form Factor(Full Load)                             | ---          | 0.9   | Vac                   |
| 最大制动电流<br>Maximum Braking Current                                       | ---          | 100% 峰值电流 ( $I_p$ )<br>100% of $I_p$ (Peak Current) | ---                   |
| 散热<br>Cooling   | ---          | 80 x 80 x 38 风扇 x3<br>3 fan 80 x 80 x 38            | ---                   |
| 风扇流量<br>Flow Rate   | ---          | 234 x 3   | m <sup>3</sup> / hour |
| 尺寸 (HxDxW)<br>Dimensions (HxDxW)  | ---          | 612 x 350 x 242.2                                   | mm                    |

<sup>(1)</sup> $V_{in}=380Vac$ ,  $V_{out}=V_{in} \times 0.95$ , 环境温度为 40°C, PWM 控制频率为 8kHz; /  $V_{in}=380Vac$ ,  $V_{out}=V_{in} \times 0.95$ ,  $T_{amb}=40^\circ C$ , Comm.Freq.8kHz;

<sup>(2)</sup> 包含输入整流部分的损耗; / Including input rectifier losses;

<sup>(3)</sup> 为了使输出电流保持在额定, 电机零速时 PWM 频率会自动降低。/ PWM frequency will automatically decrease at zero speed, in order to keep nominal current output.

## 外形尺寸 Overall Dimensions



## 电机位置反馈选项 Motor Feedback Options

|  |   |
|--|---|
| 主编码器 (500kHz)<br>Main Encoder (500kHz) | 5 通道正弦编码器 (SinCos encoder), 2 个绝对值通道、2 个增量通道和 1 个零位通道<br>SinCos encoder 5 channels (2 absolute analog tracks/2 incremental analog tracks/index) |
|  | 增量编码器 (Incremental encoder), 1Vpp 或长线驱动<br>Incremental encoder (1 Vpp or Different Line Driver)   |
|  | 无传感器模式 (无电机位置反馈信号)<br>Sensorless algorithm (w/o feedback)   |
|  | EnDat 系列编码器, 支持 EnDat 1.0 - 2.2 协议 (系统默认编码器)<br>EnDat serial encoder 1.0 to 2.2 (default)   |
|  | 旋转变压器<br>Resolver   |
| 辅助编码器<br>Secondary Encoder             | Hiperface 系列编码器<br>Hiperface encoder  |
|  | 无换向信号通道的数字增量编码器 (500kHz)<br>Incremental digital encoder without commutation tracks (500kHz)   |
|  | EnDat 系列编码器<br>EnDat serial encoder   |

## 可编程信号输入 Programmable Inputs Signals

|  |  |
|--|--|
| 2 路差分 / 4 路单端模拟信号输入<br>2 differential / 4 single ended analog inputs | $\pm 10V$ (1mV) / $R_{in} = 10k\Omega$   |
| 8 路数字信号输入<br>8 digital inputs  | 20 - 30V / 对地 $R_{in} = 6.6k\Omega$<br>20 - 30V / $R_{in} = 6.6k\Omega$ to GND |
| 2 路隔离的模拟信号输入 (选配)<br>2 insulated analog inputs (optional)            | $\pm 10V$ (1mV)  |
| 8 路隔离的数字信号输入 (选配)<br>8 insulated analog inputs (optional)            | 5mA, 最大电压 24Vdc<br>5mA, 24Vdc max  |

## 可编程信号输出 Programmable Outputs Signals

|   |   |
|---|---|
| 2 路模拟信号输出<br>2 analog outputs                               | 0-10V (1mV) FS (30mA)   |
| 4 路数字信号输出<br>4 digital outputs                              | PNP 集电极开路 24V (100mA)<br>PNP open collector 24V (100mA)   |
| 1 路继电器输出<br>1 watch dog relay                               | 2A / 30Vdc, 0.25A / 250Vac 常开 (N.O.) / 常闭 (N.C.) 针脚<br>2A / 30Vdc, 0.25A / 250Vac, NO/NC contacts |
| 2 路隔离的模拟信号输出 (选配)<br>2 insulated analog outputs (optional)  | $\pm 10V$ (1mV) FS (30mA)   |
| 2 路隔离的数字信号输出 (选配)<br>2 insulated digital outputs (optional) | 开关量, 9-28V / 2A<br>On.off switch, 9-28V / 2A  |

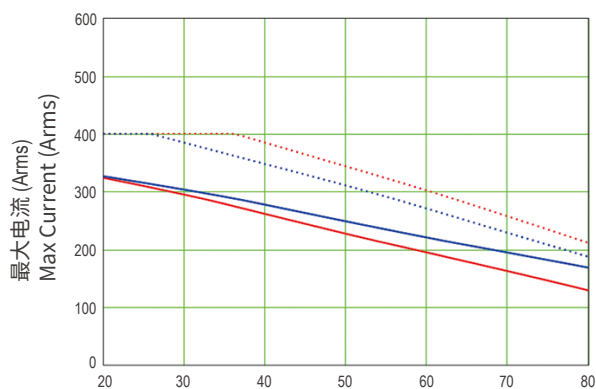
## 硬件配置 Hardware Configuration

|  |  |   |
|--|--|---|
| 处理器<br>Processor Speed                 | 80MIPS $\mu$ C + FPGA / 120MIPS $\mu$ C + FPGA 增强版<br>80MIPS $\mu$ C + FPGA / 120MIPS $\mu$ C + FPGA Extreme Version | 可选<br>Optional  |
| 工作频率<br>Task Frequency                 | 电流环采样频率<br>Current / drive monitoring  | 1MHz  |
|  | 位置环 / 速度环频率<br>Position / speed loop   | 8kHz  |
|  | PLC 快速任务扫描频率<br>PLC fast task  | 8kHz  |
|  | PLC 慢速任务扫描频率<br>PLC slow task  | 15.625Hz to 1 kHz (可配置)<br>15.625 Hz to 1 kHz (user-programmable) |
| 位置模式可用<br>Position Loop Mode Available | 目标位置寄存器位宽<br>Target position register  | 32 or 64 bits   |
|  | 全数字 Id / Iq 控制<br>Full digital control Id/Iq   | 最高可达 16kHz<br>updated 16 kHz                                      |



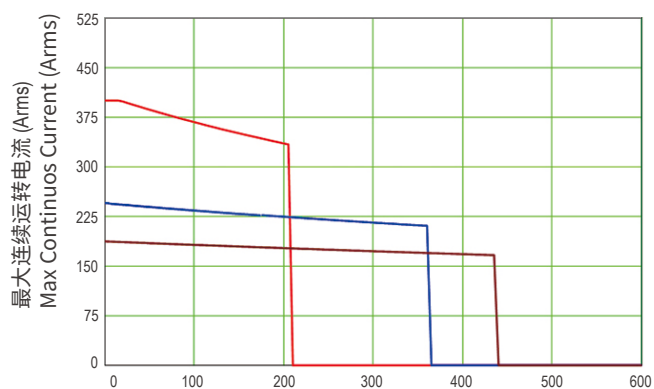
# 驱动器运行区间 Drive Operational Area

AxN 200.400.4



环境温度 (°C)  
Ambient Temperature (°C)

- 连续运转电流 (Vout=380Vac, Comm. Freq. 8KHz)  
Continuos Current (Vout=380Vac, Comm. Freq. 8KHz)
- 连续运转电流 (Vout=460Vac, Comm. Freq. 8KHz)  
Continuos Current (Vout=460Vac, Comm. Freq. 8KHz)
- ..... 零速电流 (Vout=380Vac, Comm. Freq. 8KHz)  
Zero Speed Current (Vout=380Vac, Comm. Freq. 8KHz)
- ..... 零速电流 (Vout=460Vac, Comm. Freq. 8KHz)  
Zero Speed Current (Vout=460Vac, Comm. Freq. 8KHz)



输出电压 (Vac)  
Output Voltage (Vac)

- 连续运转电流 (Vout=220Vac, Comm. Freq. 8KHz)  
Continuos Current (Vout=220Vac, Comm. Freq. 8KHz)
- 连续运转电流 (Vout=380Vac, Comm. Freq. 8KHz)  
Continuos Current (Vout=380Vac, Comm. Freq. 8KHz)
- 连续运转电流 (Vout=460Vac, Comm. Freq. 8KHz)  
Continuos Current (Vout=460Vac, Comm. Freq. 8KHz)



## 菲仕总部 PHYSIS HEADQUARTER

宁波菲仕技术股份有限公司

Ningbo Physis Technology Co., Ltd.

浙江省宁波市北仑区小港安居路 308 号

No.308, Xiaogang Anju Road, Beilun District, Ningbo, China

总台热线 /Tel: +0086-(0)574-26922600

### 市场销售 Marketing & Sales

销售热线 /Tel: +0086-(0)574-23459197

邮箱 /E-mail: Sales@physis.com.cn

### 售后服务 After Sales

服务热线 /Tel: +0086-(0)574-23459183

+0086-(0)574-23459182

邮箱 /E-mail: Aftersales@physis.com.cn



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